

FIG. 1

FIG. 2 is a block diagram of a system 200. The system 200 includes a library 200, two hosts 202 and 203, two drives 206 and 207, and a robotic device 210. Host 202 is connected to drive 206 via a C,D interface 212. Host 203 is connected to drive 207 via a C,D interface 216. Drive 206 is connected to the robotic device 210 via a C interface 228. Drive 207 is connected to the robotic device 210 via a C interface 226. The robotic device 210 is connected to drive 206 via a C interface 230. The system 200 is enclosed in a rounded rectangle.

200 LIBRARY

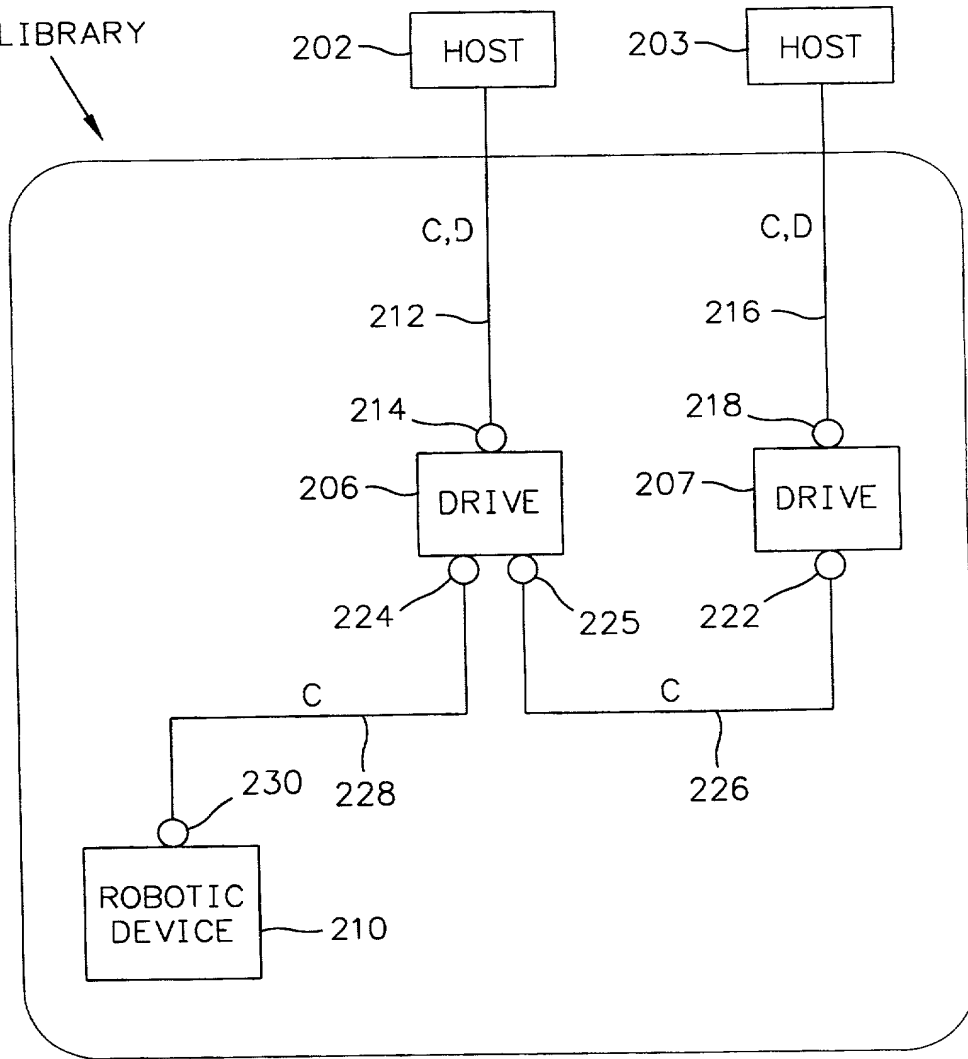
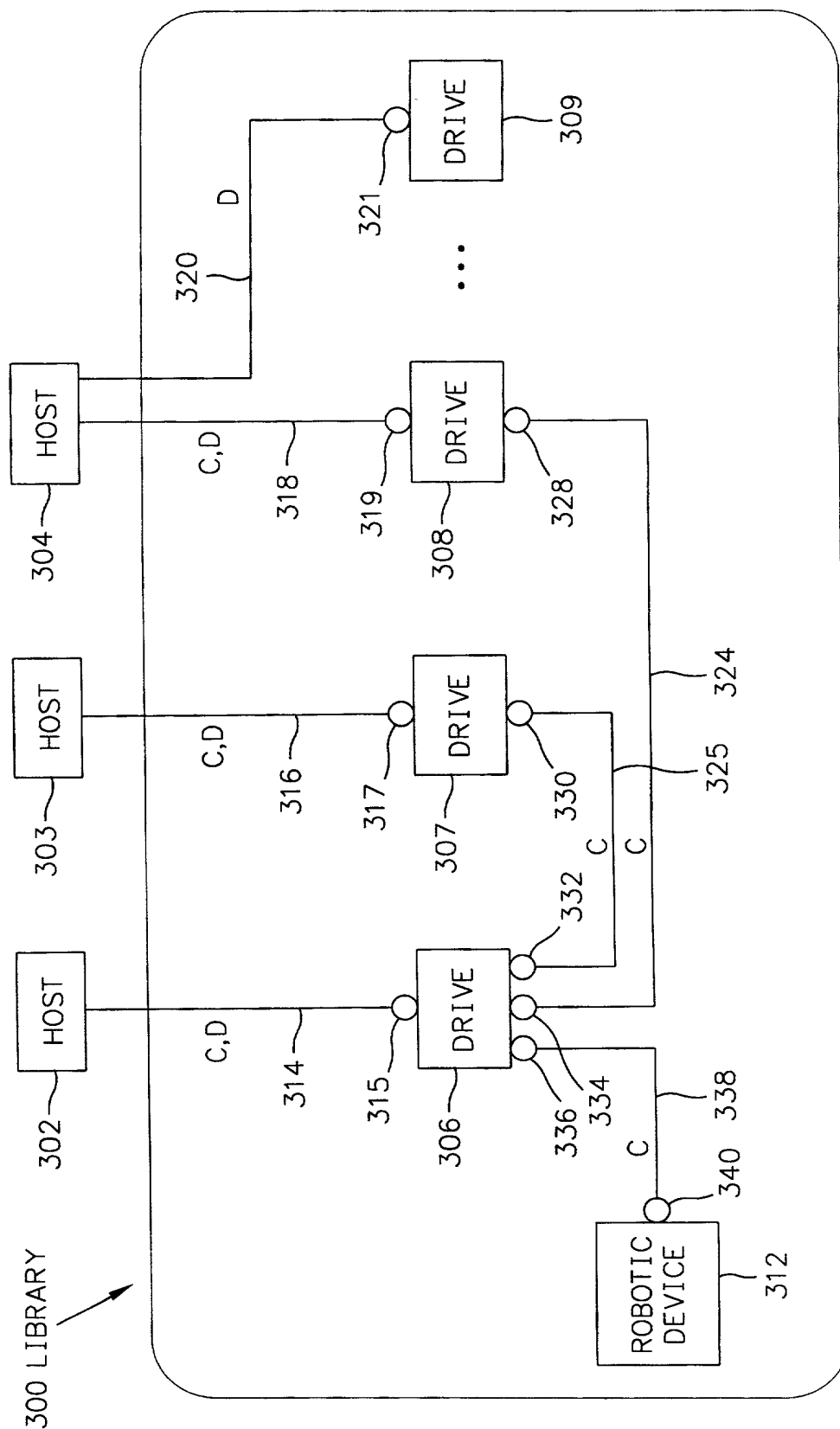


FIG. 2



**FIG. 3**

400 LIBRARY

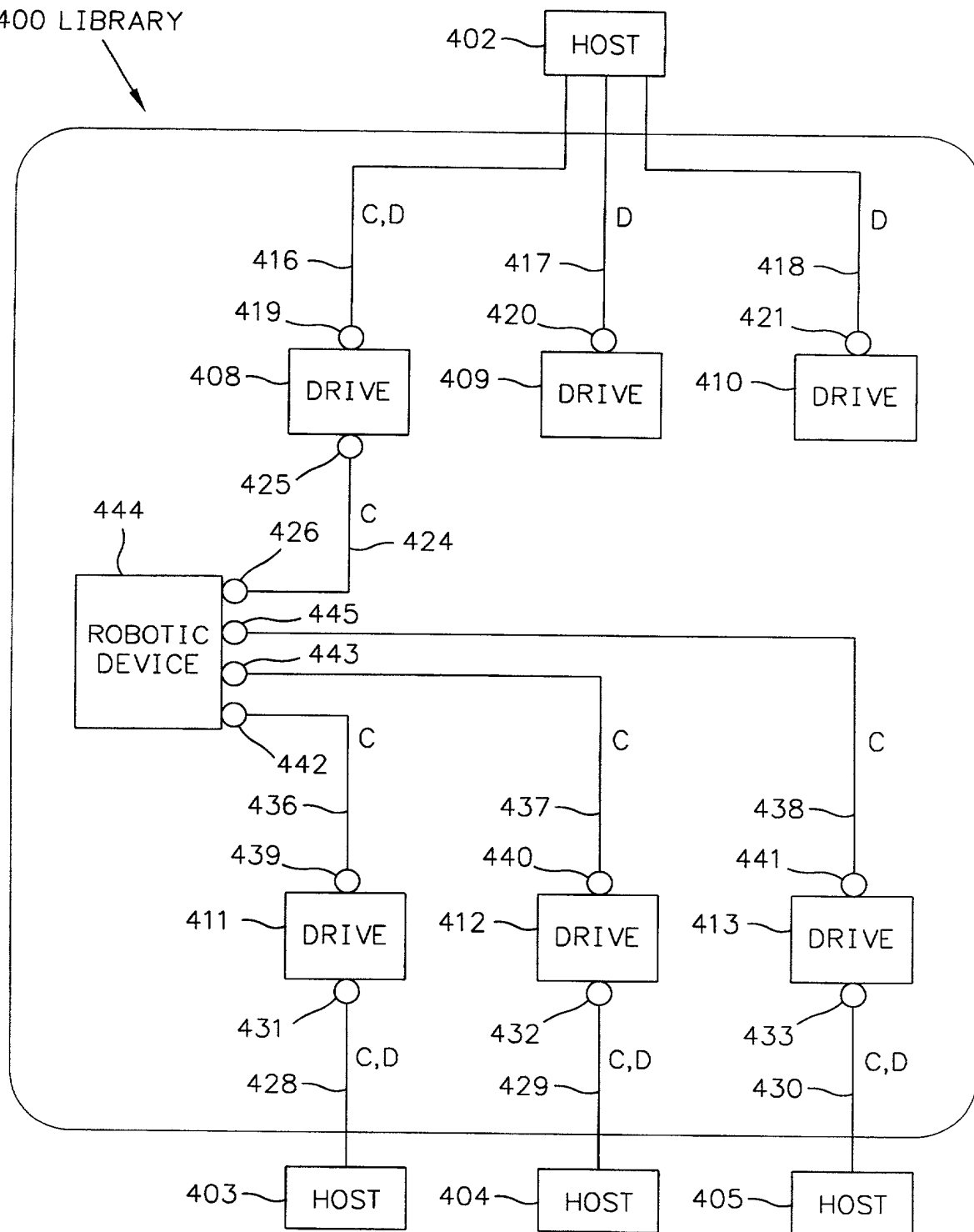


FIG. 4

500 LIBRARY

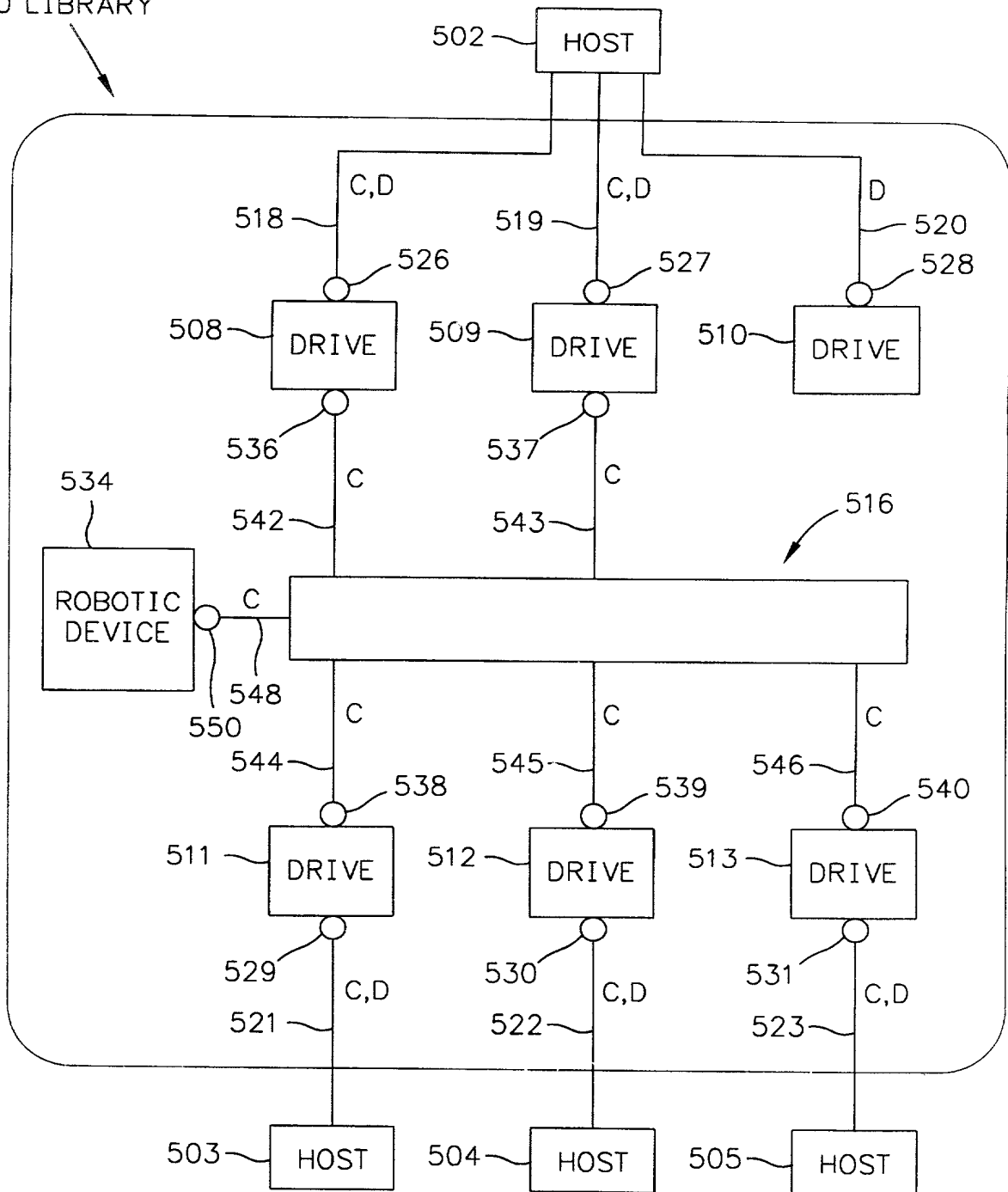


FIG. 5

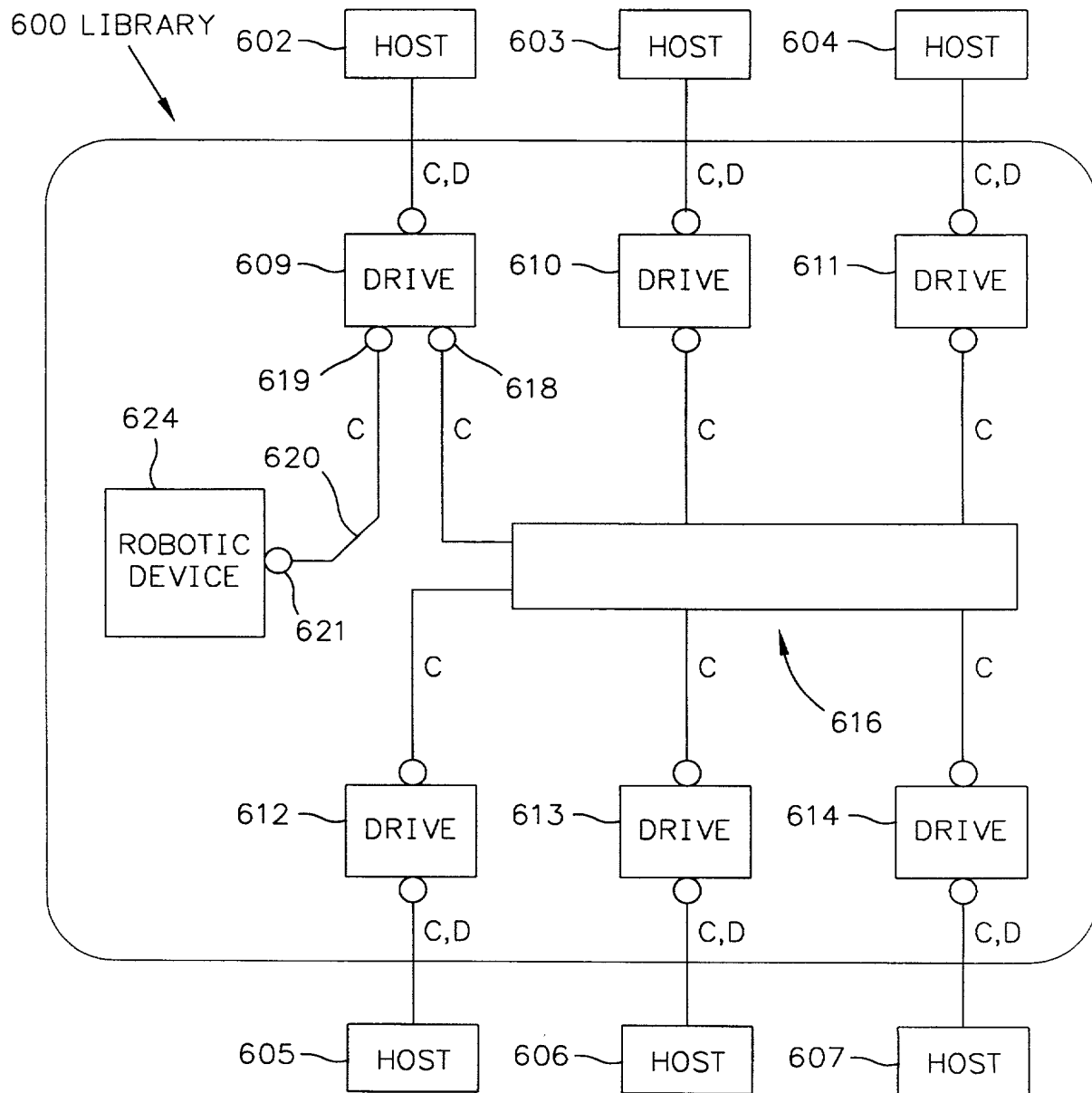


FIG. 6

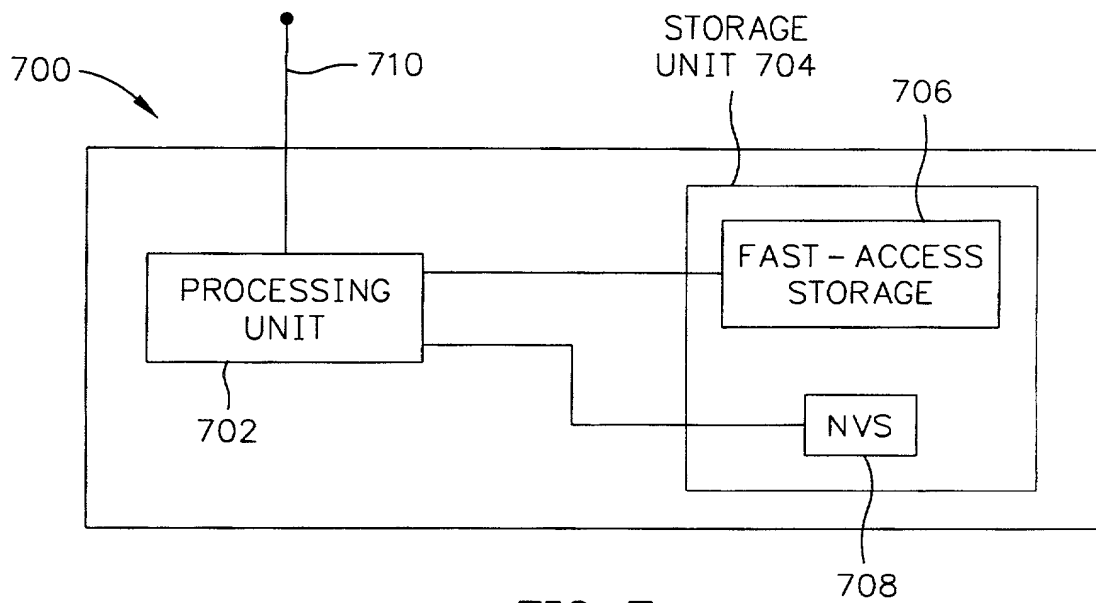


FIG. 7

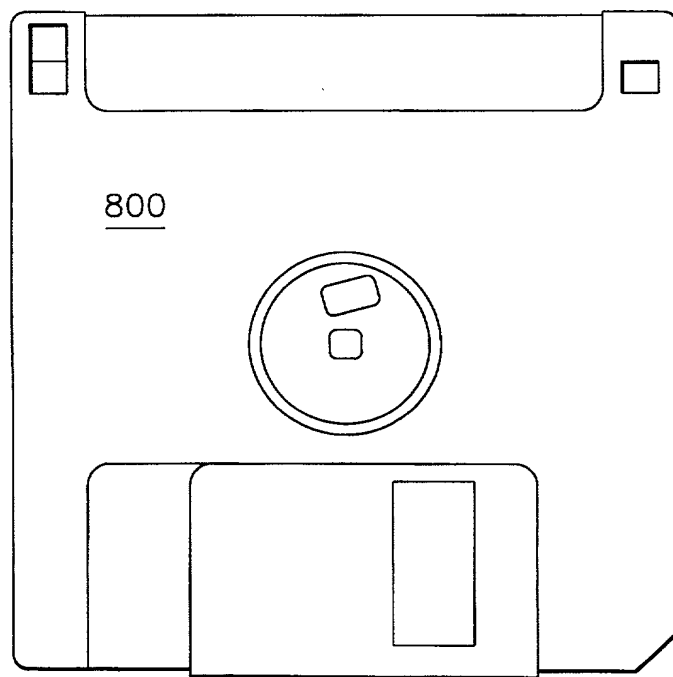


FIG. 8

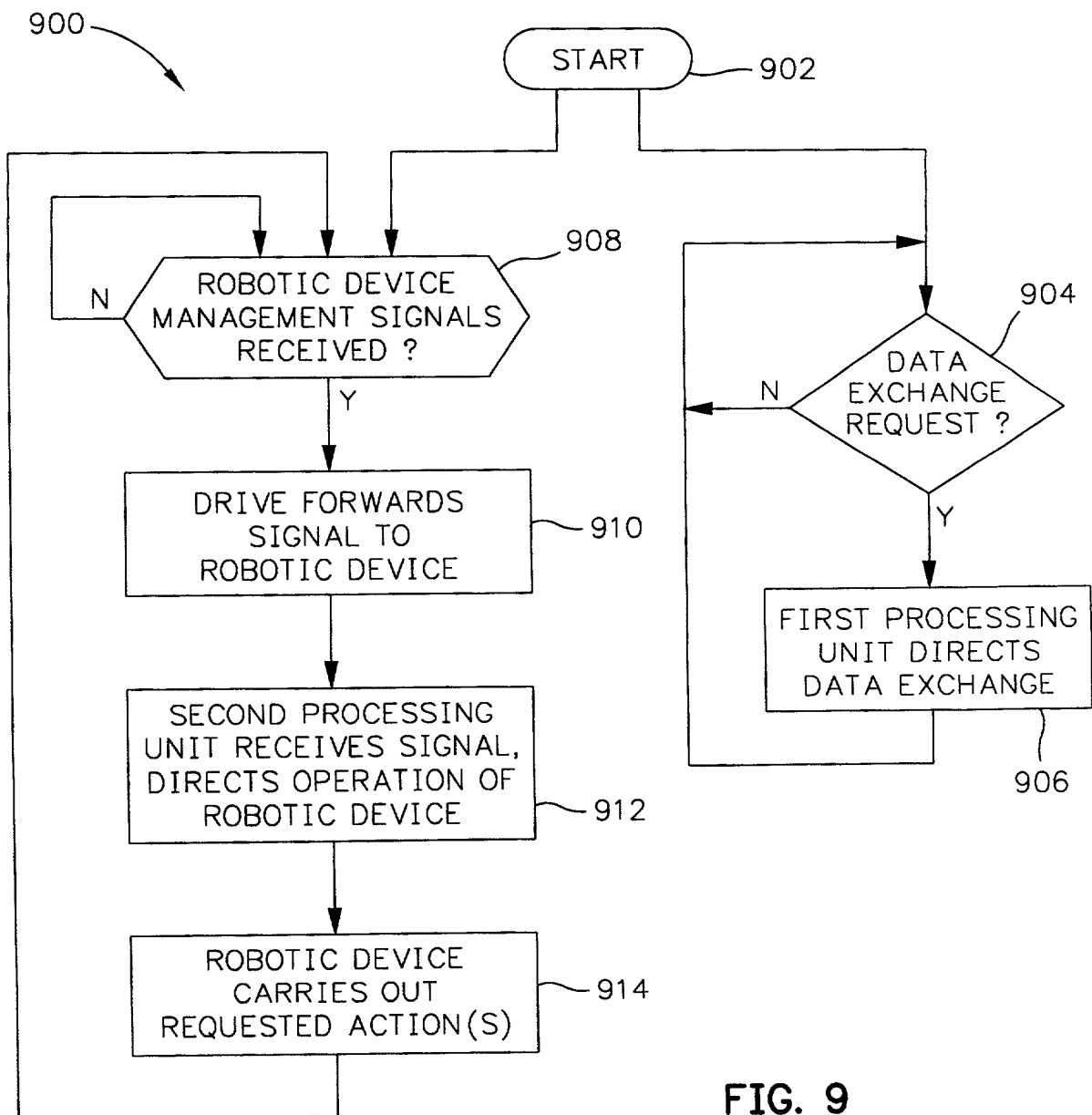


FIG. 9



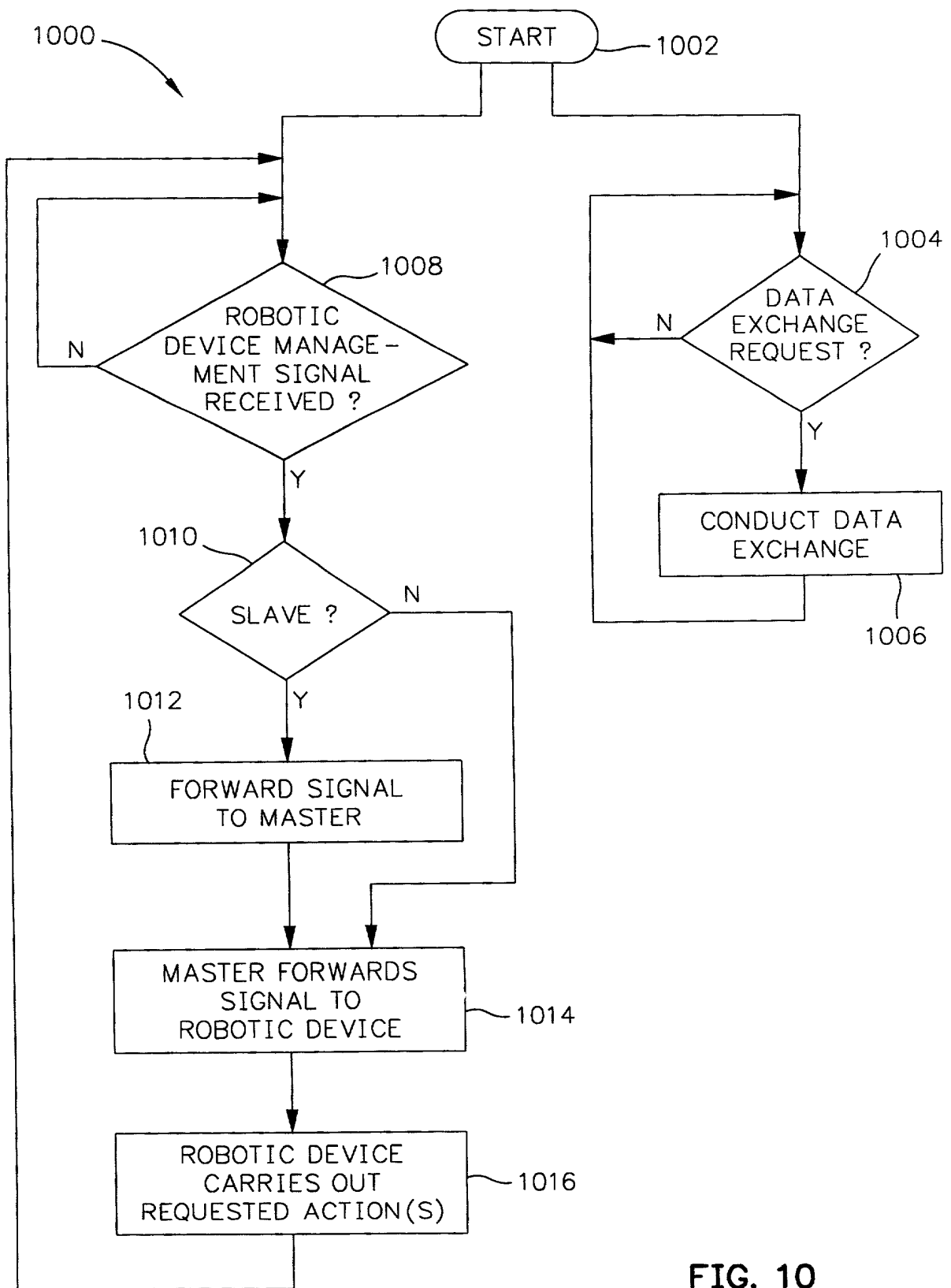


FIG. 10

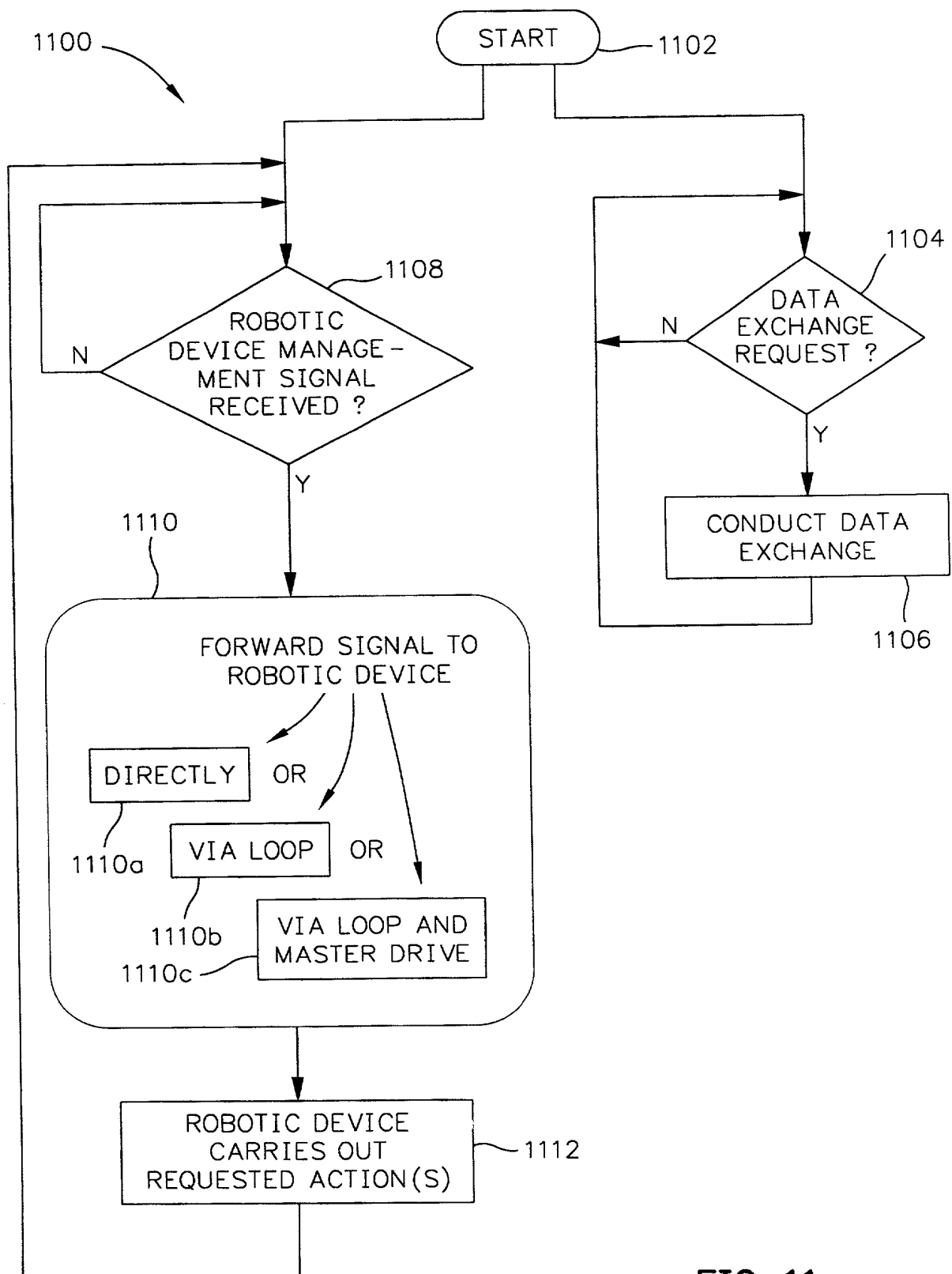
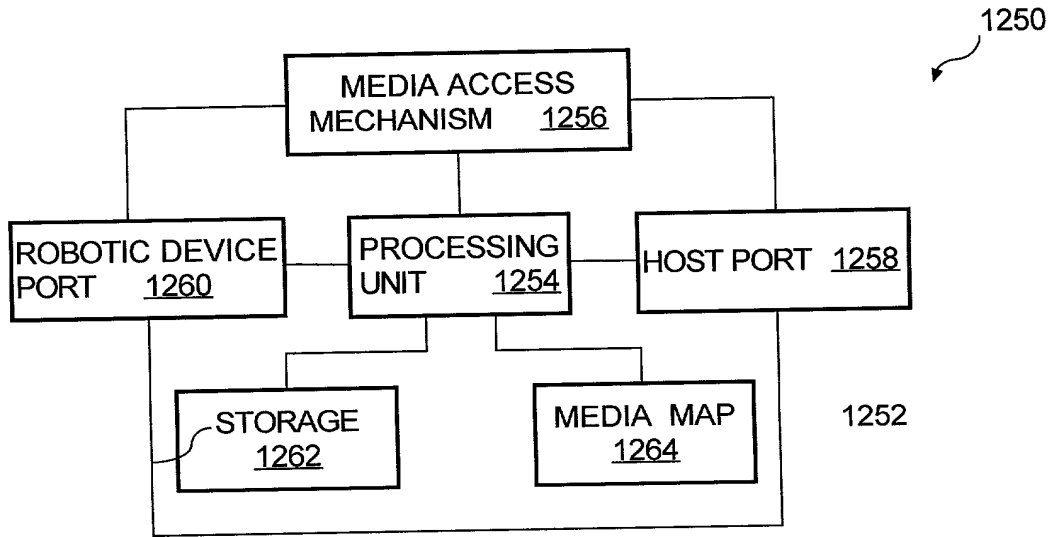


FIG. 11

**FIGURE 12**



**FIGURE 13**

